

# Robust sparse estimation: An overview

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# Overview

- ▶ **Background**
  - ▷ Algorithmic framework
- ▶ Polynomial-time algorithms
  - ▷ Some improvements
- ▶ Quadratic-time algorithms
- ▶ Subquadratic-time algorithms

# Introducing structured robust estimation

- ▶ So far, we have seen *unstructured* parameter estimation

**Problem statement.** (Robust mean estimation)

Let  $\mathcal{P}$  be an unknown nice distribution over  $\mathbb{R}^d$  with mean  $\mu$

Input: corrupted samples from  $\mathcal{P}$

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in this talk: sparsity

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**This talk:** Utilizing the structure of sparsity **robustly**.

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**Relaxed goal:** Achieving  $\text{poly}(k, \log d)$  sample complexity, **efficiently**

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- ▶ Key insight [DKKLMS16; LRV16]: For any direction  $v$ ,
  - ▷ The sample mean is accurate **if** the sample variance is bounded
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### Algorithmic template: robust (dense) estimation

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**How to design an efficient subroutine?**

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**Better certificates  $\implies$  better algorithms**



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- ▶ Near-optimal asymptotic error
  - ▶ Near-optimal *computational* sample complexity
  - ▶ Runtime: polynomial but existing SDP solvers are **impractical**
    - ▷ Current bounds:  $\Omega(d^4)$  time
    - ▷ **Open problem:** design faster solvers for this SDP

## Proof sketch: stability with a small number of samples

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$$\max_{S' \subset S: \text{large}} \|\Sigma_{S'}\|_{\mathcal{X}_k} \lesssim \|\Sigma_S\|_{\mathcal{X}_k}$$

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triangle inequality

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$$\begin{aligned} \max_{S' \subset S: \text{large}} \|\Sigma_{S'}\|_{\mathcal{X}_k} &\lesssim \|\Sigma_S\|_{\mathcal{X}_k} \leq 1 + \|\Sigma_S - \mathbf{I}\|_{\mathcal{X}_k} \\ &\leq k \|\Sigma_S - \mathbf{I}\|_{\infty} \end{aligned}$$

Hölder's inequality

## Proof sketch: stability with a small number of samples

$$\mathcal{X}_k := \{\mathbf{M} \succeq 0 : \text{tr}(\mathbf{M}) = 1, \|\mathbf{M}\|_1 \leq k\}$$

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- ▶ Algorithm: Filtering (with SDP relaxation)
- ▶ SDP-Stability: For all large subsets  $S'$  of  $S$ :
  - ▷ (Mean)  $\sup_{v:\text{sparse}} \langle v, \mu_{S'} - \mu \rangle$  is small
  - ▷ (Covariance)  $\|\Sigma_{S'} - \mathbf{I}\|_{\mathcal{X}_k}$  is small
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Hoeffding's inequality  
and union bound

# Overview

- ▶ Background
  - ▷ Algorithmic framework
- ▶ **Polynomial-time algorithms**
  - ▷ **Some improvements**
- ▶ Quadratic-time algorithms
- ▶ Subquadratic-time algorithms

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**Can we close this gap?**

## Heavy-tailed distributions: improved sample complexity

Theorem: [DKLP22]

$\mathcal{P}$ :  $k$ -sparse mean  $\mu$ , bounded covariance, and degree-four\* moments.  
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holds at the population ( $n \rightarrow \infty$ ) by Markov

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**Theorem:** sparse rounding (worst-case) [DKLP22]

Given  $\mathbf{M} \in \mathcal{X}_k$ , there is a random matrix  $\mathbf{Q}$

- ▶ w.h.p.,  $\mathbf{Q} \in \mathcal{A}_{k,P}$
- ▶  $x^\top \mathbf{M} x \gg 1$  for clipped  $x$  implies  $\mathbb{P}_{\mathbf{Q}}(x^\top \mathbf{Q} x \gg 1) \geq 0.4$

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Suppose the distribution has bounded  $t$ -th moments;  $t \gg 1$

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- ▶ We want a practical function  $f(\cdot)$ :
  - ▷  $\|\mathbf{A}\|_{\text{op},k} \leq f(\mathbf{A})$
  - ▷  $f(\boldsymbol{\Sigma} - \mathbf{I})$  is bounded for clean data **and all large subsets** (stability)
- ▶ Suppose  $f(\mathbf{A}) = \sup_{\mathbf{B} \in \mathcal{B}} \langle \mathbf{B}, \mathbf{A} \rangle$ .
- ▶ Desirable properties of  $\mathcal{B}$ :
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  - ▷ practical to search for  $\mathbf{B}^*$  ✓
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$$\|\mathbf{A}\|_{\text{op},k} := \sup_{v:\text{sparse}} |v^\top \mathbf{A} v|$$

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Theorem: [DKKPS19]

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# Overview

- ▶ **Background**
  - ▷ Algorithmic framework
- ▶ Polynomial-time algorithms
  - ▷ Some improvements
- ▶ Quadratic-time algorithms
- ▶ **Subquadratic-time algorithms**

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Given  $\epsilon$ -contaminated samples from  $\mathcal{N}(\mu, I)$  on  $\mathbb{R}^d$  with  $k$ -sparse  $\mu$

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- ▶ **Open questions:**
  - ▷  $k^2$  sample complexity
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  - ▷ a wider family of distributions (same as [DKKPS19])

## Proof idea: Algorithm blueprint

**Algorithmic template** from [DKKPS19].

1. While  $\|\Sigma - \mathbf{I}\|_{\text{Fr},k^2}$  large:
  - 1.1 Filter points and update  $\Sigma$
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Takes  $d^2$  time

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Strongly correlated coordinates

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**How to find  $H$  in subquadratic time?**

$$H := \{(i, j) : i \neq j, |\Sigma_{i,j}| \gg \rho\}$$

## Connections to correlation detection

Definition: Two vectors  $x, y \in \mathbb{R}^n$  are  $\rho$ -correlated if  $\left| \left\langle \frac{x}{\|x\|_2}, \frac{y}{\|y\|_2} \right\rangle \right| \geq \rho$

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# Filtering using fast correlation detection

While  $\|\Sigma - \mathbf{I}\|_{\text{Fr}, k^2}$  large:

Filter outliers

## Algorithm outline.

1.  $H \leftarrow \{(i, j) : |\Sigma_{i,j}| \geq \rho\}$   $\rho = 1/k$
2.  $J \leftarrow \{(i, j) : |\Sigma_{i,j}| \geq \tau\}$   $\tau = \rho^{100}$
3. **While**  $|H| \gg \text{poly}(k)$ :
  - ▷ **If**  $|J| = o(d)$ :
    - ▷ Use [Val15](#) to find  $H$  and filter
  - ▷ **Else**
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How to calculate size of  $J$

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- ▷ **If**  $|J| = o(d)$ : How to calculate size of  $J$ 
  - ▷ Use [Val15] to find  $H$  and filter
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**Size of  $J$ :** randomly sample  $d^{1.5}$  many  $\{(i, j)\}$  & count  $\tau$ -correlation

- ▶ whp,  $\Omega(\sqrt{d})$  hits **iff**  $|J| = \Omega(d)$

# Filtering using fast correlation detection

While  $\|\Sigma - \mathbf{I}\|_{\text{Fr}, k^2}$  large:

Filter outliers

## Algorithm outline.

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**Filter:** If many entries bigger than  $\tau$ , then  $\|\Sigma - \mathbf{I}\|_{\text{Fr}, \text{poly}(1/\tau)} \gg 1$

- ▶ Can filter **if** stability holds with  $k' = \text{poly}(1/\tau)$

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## The complete algorithm.

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# Conclusion

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- ▶ What we didn't discuss?
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**Happy to chat more**

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